

BCM-12

Battery Charge Monitor

Installation and User Manual for the BCM – 12 Battery Charge Monitor.

Full Version

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Thank You For Purchasing This DynaGen Product

Please Read Manual Before Installing Unit

Receipt of Shipment and Warranty Return Information

Upon receipt of shipment, carefully remove the unit from the shipping container and thoroughly examine the unit for shipping damage. In case of damage, immediately contact the carrier and request that an inspection report be filed prior to contacting DynaGen.

All returned items are to be shipped prepaid and include a Return Material Authorization (RMA) number issued by DynaGen. RMA forms are available by contacting DynaGen Technical Support through the contact methods listed below.

Limited Warranty

DynaGen will repair or replace any BCM, which proves to be defective under normal and proper use within **Two Years** from the date of shipment. This constitutes the only warranty and no other warranty shall be implied.

We welcome your comments and suggestions. Please contact us at:

DynaGen Technologies Inc. Phone: 1-888-396-2436 (902) 562 0133 Fax: (902) 567 0633 Email: support@dynagen.ca WEB SITE: www.dynagen.ca

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SPECIFICATIONS

Operating VDC limits:	(4.75 VDC min 18VDC max.)
Standby current draw:	12 mA
Operating current draw:	160 mA
Operating temperature range:	$-20^{\circ} \text{ C} \Rightarrow +85^{\circ} \text{ C}$
Operating humidity range:	$0 \Rightarrow 95\%$ non-condensing
Run output:	5 Amps max. continuous sourcing(+bat) output
High/Low pot adjustment Range	10 – 15 VDC
Actual unit weight:	0.45 lb.
Shipping weight:	1 lb. (0.45kg)
Unit dimensions:	3.25" x 3.25" x 0.5"
Shipping dimensions:	4" (10.16cm) x 4" (10.16cm) x 3" (7.62cm)

WIRING INSTALLATION GUIDELEINES

Danger: Never work on the engine while its power is on. This Battery Charge Monitor does not generate a warning signal prior to automatic engine start. Warning signs should be placed on engine equipment indicating this important safety measure.

Following these instructions will help avoid common installation problems during wiring and setup.

- Battery (Terminal 1 & 2) must be disconnected before any wiring connections are made. Battery disconnection can easily be accomplished by removing terminal block from BCM unit.
- Wire length from the BCM unit to operating equipment, should not exceed 30 feet. Longer runs may require the use of heavier gauge wiring.
- Do not connect high voltage AC circuits to the BCM unit.

Wiring size should be minimum 18AWG. Use stranded wire, since solid wire has a tendency to crack, break and loosen over time.

NOTE:

- When making connections to BCM's removable terminal block, ensure that there are no wire strands that are exposed. Exposed strands may cause shorting to adjacent wiring terminals.
- Ensure that wire connections to removable terminal block are securely fastened, since vibrations have a tendency to loosen wiring connections over time.

Terminal	Wire Size	Current Max.	Function	
1	14 - 18	10A	Battery positive (+)	
2	14 - 18	10A	Battery positive (+)	
3	14 - 18	10A	Battery negative (-)	
4	14 - 18	10A	Battery negative (-)	
5	14 - 18	10A	Start/Run Relay output	
6	18	0.1A	Sensing Input	
7	N/C	N/C	N/C	
8	N/C	N/C	N/C	

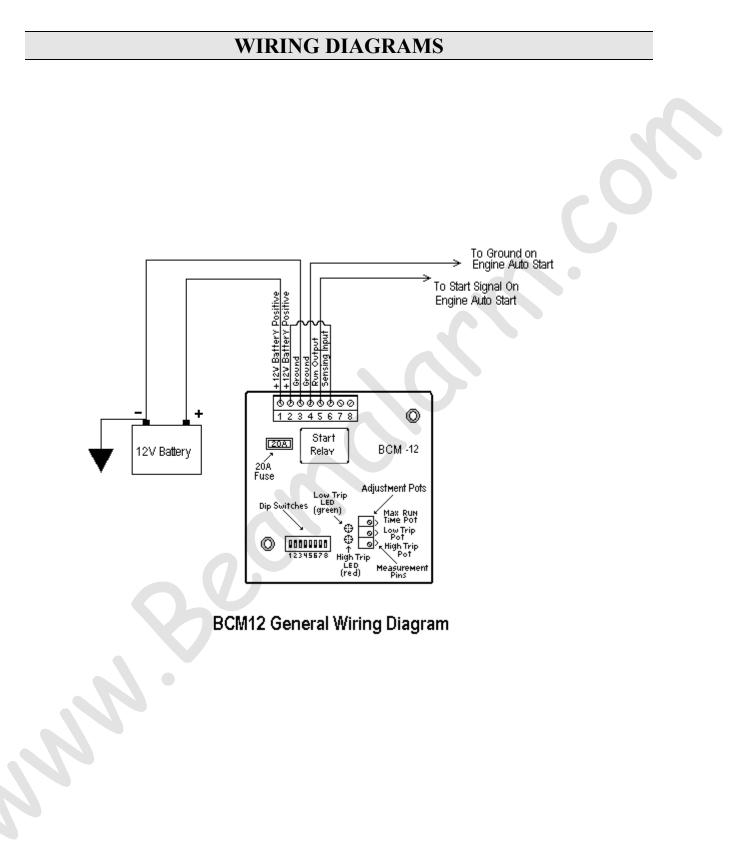
WIRING GUIDELINES

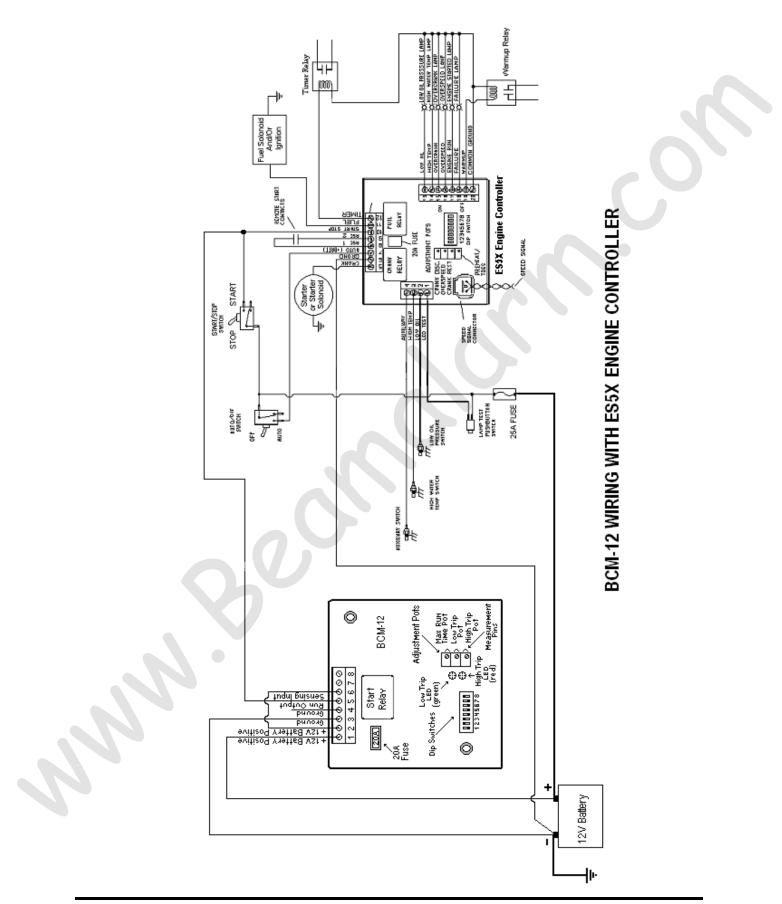
- 1. DO NOT use wire smaller than 18 AWG.
- 2. DO NOT short Run output to ground, as this will cause 20A fuse to blow, and may cause damage to on board relay contacts.
- 3. Replace on board 20A fuse with similar type and rating (Replacement fuse to be Blade type MINI FUSE rated 20 Amps maximum). Never bypass fuse with jumper, as this will not protect unit in the event of a short circuit or overload condition.
- 4. DO NOT exceed the maximum rated current and voltage on the BCM output. Do not exceed 10 amps for Run output.
- 5. Do not reverse power supply connections to the BCM unit as this will result in permanent damage to unit.
- 6. Installation of a diode is not required across Run output. An internal fast switching diode is provided to protect the BCM output from inductive kick-back. However, diodes should be placed across external slave relay contacts when used to actuate any inductive loads, such as solenoids, to protect the contacts from damage caused by arcing. In addition to prolonging the useful life of the relays, placing such diodes will enormously reduce generated electrical noise.
- 7. DO NOT short potentiometer jumpers to ground, as this may result in damage to BCM unit. These jumpers are located adjacent to the potentiometers on rear of unit, they provide a method for simple and easy calibration of LOW, HIGH and RUN TIME set points.
- **8.** There is a potentiometer, which is just below the potting, adjacent to the Run relay. DO NOT attempt to adjust this pot. This pot has been calibrated at the factory and does not require field adjustment. Adjusting this pot will greatly affect the sensing accuracy of the BCM unit.
- 9. Replace On board relay with similar type and rating. Some replacement types are as follows:

•	Bosch	Part # 0 332 207 307
•	American Zettler	Part # AZ977-1A-12D
•	Aromat	Part # CM1-R-12V

TERMINAL DESCRIPTION

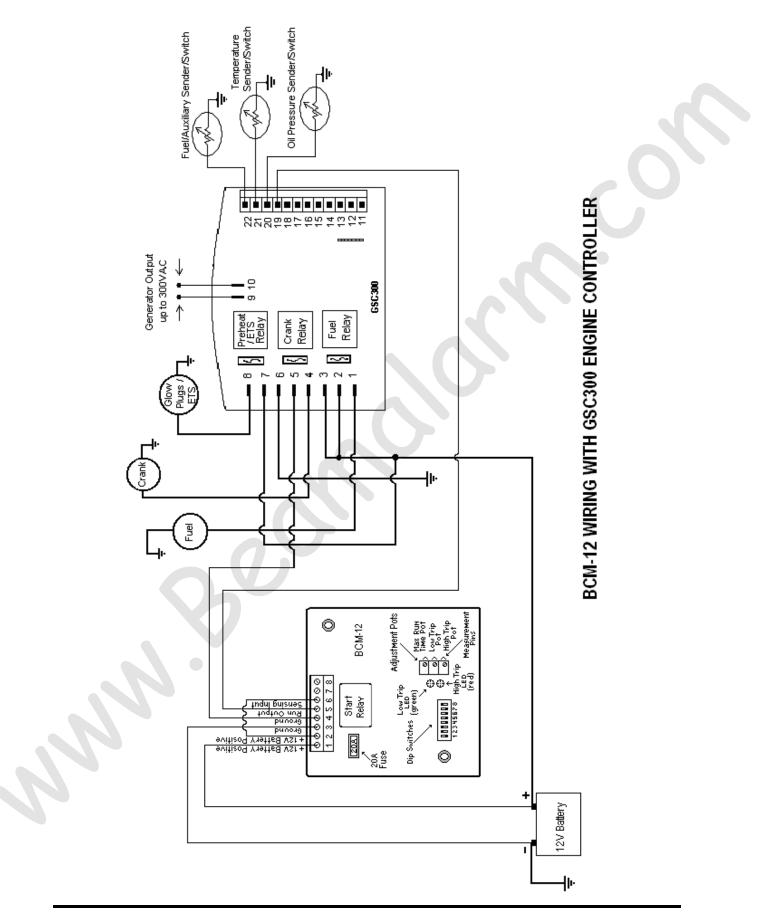
Term #	Description
1 & 2	+ Battery connection to BCM unit. This connection is fused through the on board 20 Amp replaceable fuse. This provides main power to operate BCM unit.
3 & 4	Battery ground connection for the controller module. A good ground connection, directly from the battery , is required for proper operation.
5	Run Output. This output closes to + Battery when actuated. This output energizes only after a delay on period, when a low battery condition is present.
6	Sense input. This input is used to monitor battery status. If the same battery that powers up the unit is the battery that is required to be monitored, simply connect the sense input (T#6) to one of the battery terminals (T#1 or T#2).
7	Not Used
8	Not Used





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ADJUSTMENTS AND SETUP PROCEDURES

Warning: The following procedures will require BCM operation. Be sure to follow all safety guidelines and wiring procedures.

NOTE:

"Potentiometer" is abbreviated as "pot" throughout. To increase a pot's setting, turn it clockwise; to decrease it, counter-clockwise. These Pots are 25 turns nominal, therefore turn pots fully 25 turns to ensure that you are at either the minimum or maximum setting. The rear of the BCM unit contains three adjustable pots, and an eight position DIP switch, only 3 switches are implemented on this unit.

The steps for calibration of the BCM unit to a specific system is as follows:

- 1. Calibration of LOW trip set point.
- 2. Calibration of HIGH trip set point.
- 3. Adjustment of Maximum run time setting.
- 4. Adjustment of Delay On timer setting.

1. LOW SET POINT CALIBRATION:

The low set point range spans from 10 - 15VDC. This set point is adjustable via an on board Pot. There is a green LED adjacent to the Pot (LOW), which illuminates when the sense input voltage has gone below the low set point. There is also a jumper adjacent to the LOW pot, which allows for pot calibration.

The simplest and most precise method for calibration is as follows.

- 1. Connect battery positive (10 15 VDC) to BCM terminal #1 or #2, and connect battery negative to BCM terminal #3 or #4.
- 2. Measure the voltage on the jumper adjacent to the LOW Potentiometer. The Low set point will be the voltage measured at the jumper pin +10. [LOW SETPOINT= V measured +10 VDC]

i.e. If a LOW set point of 12.1VDC is required, you must adjust the low potentiometer until the voltage at the LOW POT reads 2.1VDC.

2. <u>HIGH SETPOINT CALIBRATION:</u>

The HIGH set point range spans from 10 - 15VDC. This set point is adjustable via an on board Pot. There is a red LED adjacent to the Pot (HIGH), which illuminates when the sense input voltage has gone above the HIGH set point. There is also a jumper adjacent to the HIGH pot, which allows for pot calibration.

The simplest and most precise method for calibration is as follows.

- 1. Connect battery positive (10 15 VDC) to BCM terminal #1 or #2, and connect battery negative to BCM terminal #3 or #4.
- Measure the voltage on the jumper adjacent to the HIGH Potentiometer. The HIGH set point will be the voltage measured at the jumper pin +10. [HIGH SETPOINT= V measured +10 VDC]

i.e. If a HIGH set point of 14.2VDC is required, you must adjust the HIGH potentiometer until the voltage at the HIGH POT reads 4.2VDC.

3. MAXIMUM RUN TIME CALABRATION:

The Maximum Run time setting is adjustable from 0 - 512 minutes (0 - 8.5 hrs). This setting adjusts the maximum ON time for the Run output. i.e. if the HIGH set point has not been reached prior to the maximum run time, the Run output turns OFF, and the BCM waits for yet another LOW voltage condition.

Calibration of maximum run time is as follows:

- 1. Connect battery positive (10 15 VDC) to BCM terminal #1 or #2, and connect battery negative to BCM terminal #3 or #4.
- 2. Measure the voltage on the jumper adjacent to the MAX. RUN TIME Potentiometer. The MAX RUN TIME set point will be as follows:

[MAX RUN TIME = (V measured * 512)/5)]

i.e. If a MAX RUN TIME of 5 minutes is required then you must adjust the MAX RUN TIME potentiometer until the voltage at the MAX RUN TIME POT reads 0.0488 VDC.

V meas. = (MAX RUN TIME * 5)/512 = (5*5)/512

4. DELAY ON TIME CALIBRATION:

The Delay ON timer provides an adjustable delay for activation of the Run output. i.e. if the sense input voltage drops below the LOW set point, the BCM delays the activation of the Run relay for the delay ON period.

The Delay ON timer function is configurable from DIP switches 1, 2 & 3. The Delay ON timer has eight possible settings as follows:

Delay ON time (minutes)	SW1	SW 2	SW 3
0	ON	ON	ON
1	ON	ON	OFF
2	ON	OFF	ON
3	ON	OFF	OFF
4	OFF	ON	ON
5	OFF	ON	OFF
6	OFF	OFF	ON
7	OFF	OFF	OFF

You may want to record your settings below for future reference

USER SETTINGS:

LOW SETPOINT

HIGH SETPOINT

MAX. RUN TIME

DELAY ON TIME

SYSTEM OPERATING STATES

There are 3 main operating states for the Battery Charge Monitor, they are as follows:

A. IDLEB. DELAY ONC. CHARGING

IDLE:

Idle state is assumed when the unit is powered-up (power applied to +Battery terminal), but not told to run (sense input has not gone below low voltage set point). In Idle state, when sense input voltage drops below the LOW voltage set point, we proceed to the Delay ON timing state.

DELAY ON TIMING:

The Delay ON timing state ensures that the Sensing input voltage is below the low set point for a period of time. This delay prevents unnecessary starts of operating equipment. The Delay on time is adjustable via an onboard DIP SWITCH. When the delay ON time has elapsed, the BCM unit proceeds to Charging.

CHARGING:

In the charging state the BCM unit continually monitors for a high battery condition. When the sensing input voltage goes above the HIGH voltage set point, the BCM unit deenergizes the RUN relay and proceeds to the IDLE state of operation.